

Automated calibration, meta-data, and trust

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non-text search

- ▶ all (important) image search is based on associated text
- ▶ want to search the content of the *image pixels* themselves
 - ▶ holy grail of computer vision
 - ▶ enormous commercial value
 - ▶ obviates *trusting* the associated meta-data
- ▶ we have solved this in one *tiny* domain

Astrometry.net: Web Edition

Required Information

Identification

We need your email address to send you your results.

Email:

Name:

☐ Remember me

Field to solve: select one of the following:

In order to solve your field, we need either an image of your field (as a FITS, JPEG, GIF, PNG file or a URL); OR a list of star positions (as a FITS binary table or text file).

☐ Image file:

Your JPEG, GIF, PNG, or FITS image. Must be less than 250 MB!

☐ Image URL:

The URL of a JPEG, GIF, PNG, or FITS image. Must be less than 250 MB!

☐ FITS binary table:

Must contain a BINTABLE of detected objects, with X and Y pixel positions in "D" (double) or "E" (float) columns, with one object per row. The rows must be sorted by brightness with the brightest object first.

• FITS file:

• X Column name:

• Y Column name:

☐ Text file:

A text file, containing two columns of digits separated

Optional Settings

Parity of your image

Flipping an image reverses its "parity". If you point a digital camera at the sky and submit the JPEG, it probably has negative parity. If you have a FITS image, it probably has positive parity. Selecting the right parity will make the solving process run faster, but if in doubt just try both.

- ☒ Try both parities simultaneously
- ☐ Positive parity image
- ☐ Negative parity image

Index to use

We use indexes to solve your fields; an index contains "landmarks" for the sky. The solving process works best when the "landmarks" are a little smaller than the size of the field to be solved. We can automatically choose a suitable index based on your pixel scale estimate, or you can select one here.

Automatic (based on image scale)

Star positional error

When we find a matching "landmark", we check to see how many of the stars in your field match up with stars we know about. To do this, we need to know how much a star in your field could have moved from where it should be.

Positional error, in pixels:

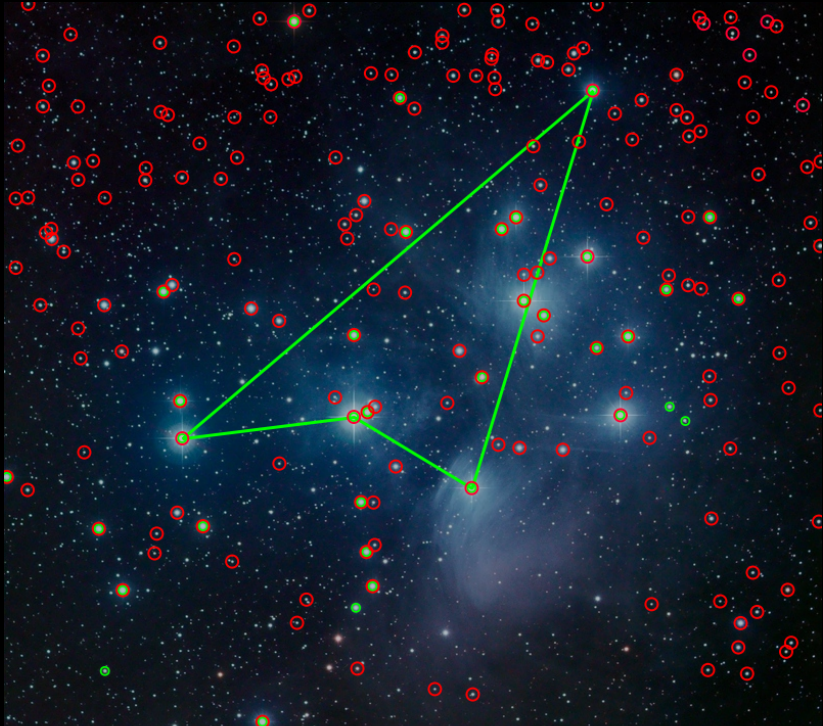
Tweak

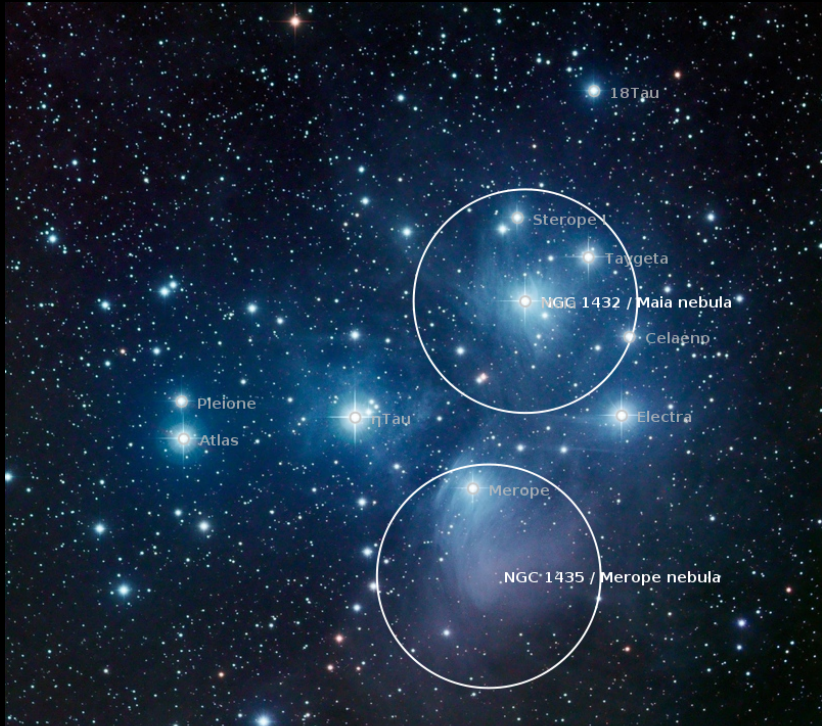
After we find a correct match, we can run a "Tweak" process which tries to fine-tune the World Coordinate System transformation by computing polynomial SIP correction terms. Sometimes this process actually makes the solution worse - we are working on an improved version.

☐ Tweak

Tweak polynomial order:

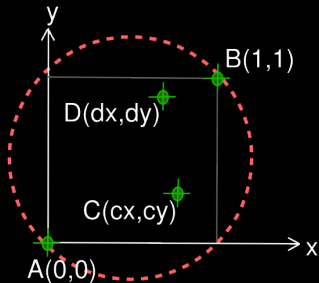
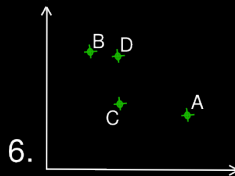
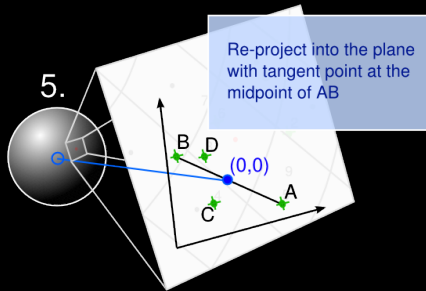




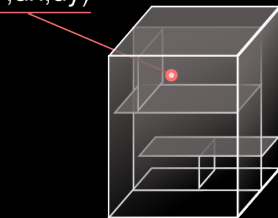


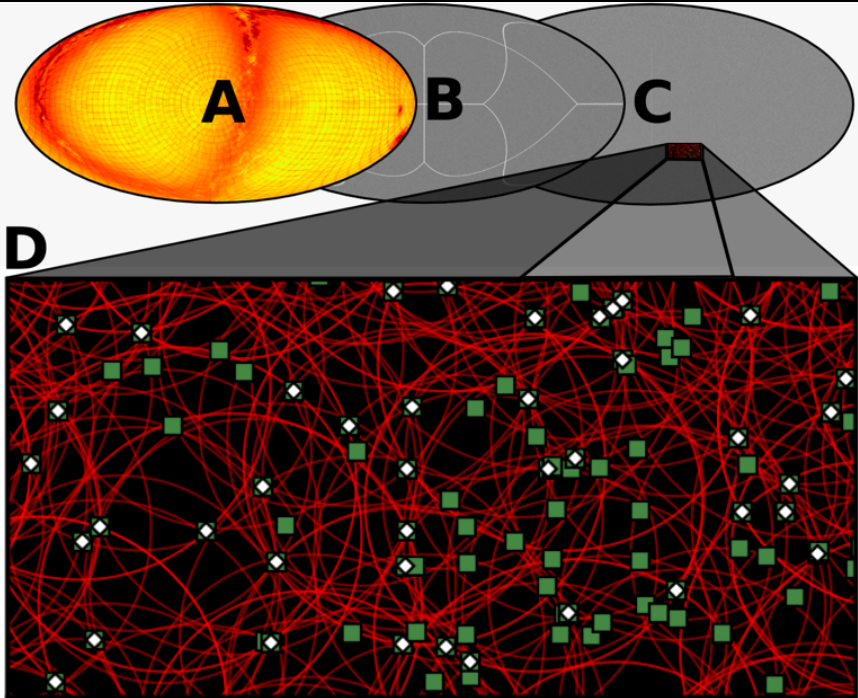
blind astrometric calibration

- ▶ determine astrometric calibration from image pixels *alone*
- ▶ geometric hashing step, verification step
- ▶ fastest kd-tree in the world (some restrictions apply)
- ▶ returns truly *trustworthy* meta-data



CODE:
(cx,cy,dx,dy)





performance

- ▶ essentially no false positives (exceptions insane)
- ▶ > 99.9 percent success rate on *SDSS* and *GALEX* imaging
- ▶ large numbers of users (amateurs, professionals, educators, robots)
- ▶ can also do other kinds of calibration:
 - ▶ wavelength bandpass
 - ▶ photometric sensitivity
 - ▶ point-spread function
 - ▶ date (to within years 2008 AJ 136 1490)
- ▶ don't believe? Sign up now at <http://astrometry.net/>

trusting data

- ▶ data that have not been used to *do science* are *wrong data*
- ▶ a practical point, not a theoretical point (see *SDSS*)
- ▶ the “Virtual Observatory” has no trust model
- ▶ science is the *ultimate functional testing environment*

maximally heterogeneous data

- ▶ we would like to do simultaneous work with data from amateurs and archives
- ▶ data often have unknown provenance, wrong clocks, *etc.*
- ▶ we need to calibrate, vet, verify—automatically
- ▶ we need *robots that do science*

the theory of everything

- ▶ simultaneous modeling of all astronomical imaging (arXiv/0810.3851)
- ▶ run in real time as an update system
- ▶ model parameters:
 - ▶ position and brightness of every star
 - ▶ pointing, orientation, bandpass, PSF, calibration of every image
 - ▶ camera parameters for every telescope + camera
- ▶ report “novel information content” about incoming imaging
- ▶ basis of the Open-Source Sky Survey
- ▶ calibration and vetting is produced naturally

summary

- ▶ doing automated calibration successfully *now*
- ▶ this creates a possible *trust* system for astronomy
- ▶ we would like to be doing *automated science*
- ▶ we have a model for how that might work